**Develop a python script**

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| Team ID | PNT2022TMID18889 |
| Project Name | Smart waste management system for  metropolitan cities |

Step 1: Open python idle Step2: Type the program

Step 3: Then click on file and save the document Step 4: Then click on Run then Run Module

Step 5: output will be appeared in the idle window

# Python script

import requests import json

import ibmiotf.application import ibmiotf.device import time

import random import sys

# watson device details

organization = "4yi0vc" devicType = "BIN1" deviceId = "BIN1ID" authMethod= "token" authToken= "123456789"

#generate random values for randomo variables (temperature&humidity)

def myCommandCallback(cmd): global a

print("command recieved:%s" %cmd.data['command']) control=cmd.data['command']

print(control)

try:

deviceOptions={"org": organization, "type": devicType,"id": deviceId,"auth-method":authMethod,"auth-

token":authToken}

deviceCli = ibmiotf.device.Client(deviceOptions) except Exception as e:

print("caught exception connecting device %s" %str(e)) sys.exit()

#connect and send a datapoint "temp" with value integer value into the cloud as a type of event for every 10 seconds deviceCli.connect()

while True:

distance= random.randint(10,70) loadcell= random.randint(5,15)

data= {'dist':distance,'load':loadcell}

if loadcell < 13 and loadcell > 15: load = "90 %"

elif loadcell < 8 and loadcell > 12: load = "60 %"

elif loadcell < 4 and loadcell > 7: load = "40 %"

else:

load = "0 %"

if distance < 15:

dist = 'Risk warning:' 'Dumpster poundage getting high, Time to collect :) 90 %'

elif distance < 40 and distance >16:

dist = 'Risk warning:' 'dumpster is above 60%'

elif distance < 60 and distance > 41: dist = 'Risk warning:' '40 %'

else:

dist = 'Risk warning:' '17 %'

if load == "90 %" or distance == "90 %":

warn = 'alert :' ' Dumpster poundage getting high, Time to collect :)' elif load == "60 %" or distance == "60 %":

warn = 'alert :' 'dumpster is above 60%' else :

warn = 'alert :' 'No need to collect right now ' def myOnPublishCallback(lat=10.678991,long=78.177731):

print("BUS STAND, SALEM")

print("published distance = %s " %distance,"loadcell:%s " %loadcell,"lon = %s " %long,"lat = %s" %lat) print(load)

print(dist) print(warn)

time.sleep(10)

success=deviceCli.publishEvent ("IoTSensor","json",warn,qos=0,on\_publish= myOnPublishCallback)

success=deviceCli.publishEvent ("IoTSensor","json",data,qos=0,on\_publish= myOnPublishCallback)

if not success:

print("not connected to ibmiot") time.sleep(30)

deviceCli.commandCallback=myCommandCallback #disconnect the device

deviceCli.disconnect

# Screenshots Python script:

